

## Deepwater hydrate detection and characterization with Acoustic Resonance Technology (ART)

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#### **Issues Caused by Hydrates**

- Efficiency Loss: Depressurization or chemical inhibitors may be needed to prevent hydrates.
- Flow Blockage: Hydrate plugs can block fluid flow, reducing production or causing shutdowns.
- Pressure Buildup: Hydrates increase pipeline pressure, risking damage, leaks, or ruptures.
- Corrosion: Hydrates accelerate corrosion, shortening pipeline lifespan and raising maintenance costs.







#### **Alternative Flow Assurance Practices**

In a recent client survey, it was found that long production shutdowns in deepwater operations are uncommon. As a result, operators are now more willing to reduce CAPEX by shifting from expensive prevention to efficient, rapid-response technologies. This change focuses on mitigation, addressing issues as they arise rather than relying on heavy upfront investments

**Traditional Solutions:** 

• Expensive production loops, insulation, and chemical inhibitors.

New Approach :

- New replacement technology and remediation techniques
- Develop inspection tool technologies for rapid hydrate detection.



#### The Mission & Challenges

- Technique must be able to distinguish hydrate from gas or liquid
- Technique must penetrate 3-Layer
  Polyethylene (3LPE) 3.1 mm coating of the 8"
  OD Pipe
- Minimal seabed intervention, specified Line submerged under seabed up to 1-2m depth
- High-speed cost-effective ROV deployed method required with full line coverage
- Identify the exact location, size and distribution of suspected hydrate plug within 12km stretch of a water injection line off W. Africa

Pipeline Details	
Pipeline Identification	WI-8
Pipeline OD w/out Coating (mm)	235.0 / 244.5 (Variable)
Wall Thickness (mm)	15.9
Coating Thickness (mm)	3.1
Coating Type	3LPP
Pipeline OD with Coating (mm)	241.5 / 250.7
Length of Section for Inspection (km)	12 km
Water Depth (m)	1,300

### Challenge 1

#### Technique must be able to distinguish hydrate from gas or liquid





### Overview ART<sup>®</sup> Methodology





#### ART – Original Development

First industrial subsea application of the ART technology was to map air/oil/water levels in a sunken battleship from WW2.

The inspection was carried out to prepare a plan for replacing oil with water in the ballast tanks





#### **Observations from Previous Testing**

- Water and Ice (Hydrate) have very similar density
- Hydrates will typically absorb more
  acoustic energy than water
- ART is highly sensitive to changes in attenuation and therefore changes in medium



Figure 2. Example of how an ART detector would work.



#### **Hydrate Detection Testing**

#### Algorithms developed to differentiate water – gas – hydrate presence

#### **Backwall Echo**

•Reflection of an acoustic signal from the far side of the pipeline.

#### **Decay Rate**

•Refers to how quickly the acoustic signal diminishes after entering the pipe bore and is influenced by the medium (e.g., water, gas/air, hydrate/ice).







### Lab Testing in Norway

- Lab testing proved that the current configuration offered robust and repeatable results
- However, a new system system needed match the ROV speed and maintain the robustness and repeatability





### Challenge 2

## Minimal seabed intervention, and high-speed ROV deployed method with full line coverage





#### **ART vPush Development**

Pipeline Condition:

- Semi-buried pipeline.
- Client cleaned only the top 9-3 o'clock area.

Tool Adaptation:

• Tool and sensors designed to account for limited access.

Cost Savings:

- Reduced dredging time.
- Maintained tool robustness and reliability





#### **ART vPush Development**

Fast Deployment:

- Easy to integrate, ROV-operated solution.
- Designed and built in just 12 weeks.

Transducer Design:

• Circumferentially and axially offset transducers. Full coverage and minimizes signal interference.

Monitoring System:

• 4 cameras to monitor each transducer's path.

Tracking

• Odometer for accurate location-encoding of data.

Robust & Stable Design:

• Stiff frame and a compliant handle maintains transducer alignment and eliminates ROV-induced 'wobble.'





### Lab Testing in Norway

vPush incorporated four sensors running on three trigger points;

- First, back wall echo monitoring
- Second, echo threshold
- Third, echo decay





#### Challenge 3

# Identify the exact location, size and distribution of suspected hydrate plug





### **High-Speed Hydrate Detection**

- 12 km continuous scanning in 33 hrs
- Hydrate plug located and sized
- High-speed data collection minimising ROV & Vessel time
- Through-coating inspection, eliminates coating removal/reinstatment
- Minimal dredging requirements







#### **Results: High-Speed Hydrate Detection**







#### **Offshore Validation Results**



[decay/reverberation]



## Thank You! Questions?

Technologies

Applications

Robots