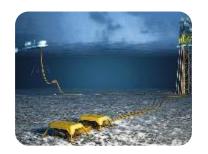


Underwater Robots for Subsea Applications



Resource Extraction



Science



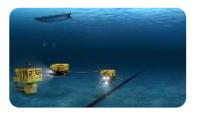
National Defence



Aquaculture



Telecommunications



Construction, Inspection and Maintenance



Archeology



Search and Recovery

Dirty

Dangerous

Distant

Dull

Deep Water

Under Ice

Nuclear plant



Subsea Operations

Reduce the Risk: 'NO man on seabed or surface'





Reduce Cost and Increase Efficiency: 'Adapt autonomous robotic solutions'

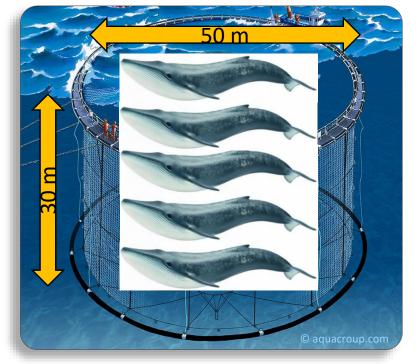


Aquaculture Industry



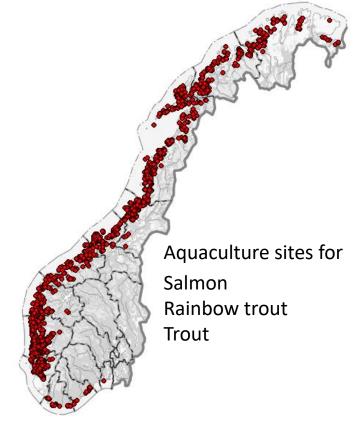
Salmon Aquaculture in Norway

- > 90% of the seafood produced in Norway is Atlantic salmon (Salmo salar)
 - = 1.3 million tonnes in 2016 (\sim 60 % of world production)
- > 165 companies with 986 sites + 98 research licenses





- Max. 200 000 fish /cage
- Slaughter weight: 5 kg /fish
- → 1 000 t fish /cage
- → Up to 15 000 t fish /site





Current Technology and Operations in Aquaculture Industry

- Complex marine operations
- Interaction with the fish
- High risk
- General lack of instrumentation



Current Robotic Solutions in Aquaculture Operations







Photo: AKVA Group



Photo: YANMAR



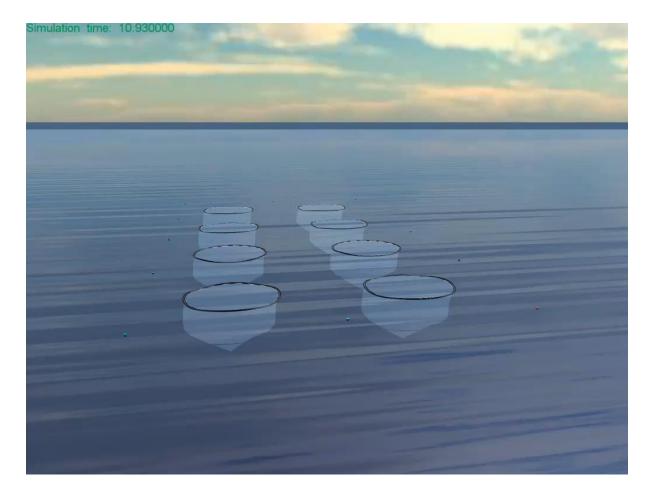
Photo: Ocein AS

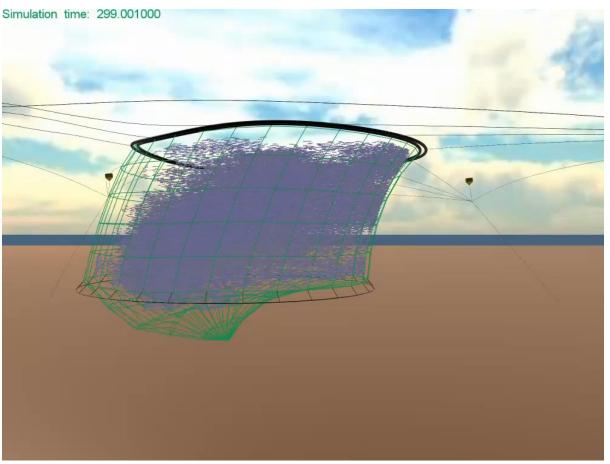
Photo: Mithal AS



Operation in Dynamically Changing Environments

Flexible and Deformable Structures











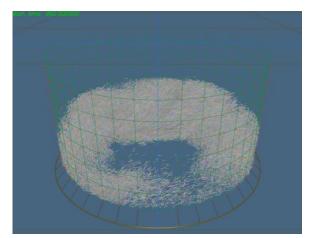
- More fish farms
- More exposed areas
- Need for autonomous operations

- Strict demands for autonomous IMR operations
- Increase welfare and reduced cost

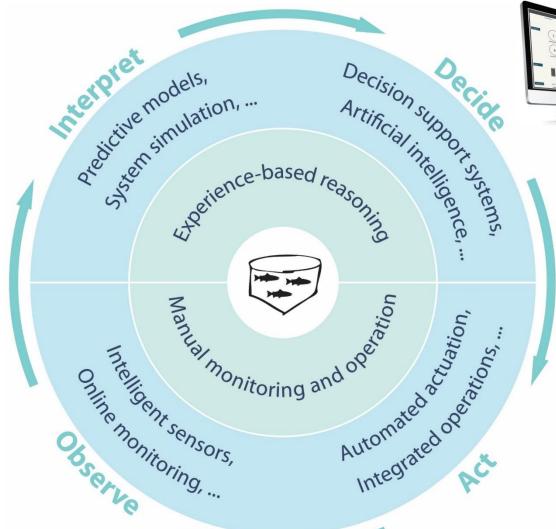
Precision Fish Farming – PFF



A new framework to improve production in aquaculture - Developed in SINTEF Ocean









SINTEF ACE – Full Scale Aquaculture Engineering Laboratory

Two seaweed farming sites located in Hitra/Frøya.









Tristeinen

Korsneset

Rataren

Hosenøya



Autonomous Aquaculture Robotic Lab - SINTEF ACE

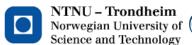
- > Fish status
- Cage and mooring inspection
- Net inspection
- Environmental monitoring
- Light intervention













EXPOSED Aquaculture Operations research centre

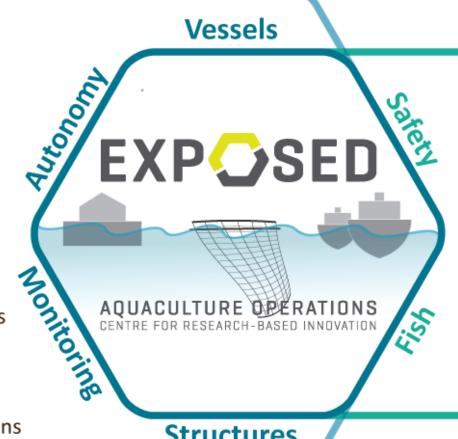
Technological innovation

AREA 1 Autonomous systems and technologies for remote operations

AREA 2 Monitoring and operational decision support

AREA 3 Structures for exposed locations

AREA 4 Vessel design for exposed operations



Requirements for sustainable production

Safety and risk management

AREA 6 Fish behaviour and welfare









Relevant Projects



MERDROV-ROV as tool for net cage operations

Developed knowledge, technology and demonstrators for semiautonomous ROV operation for net inspection and repair

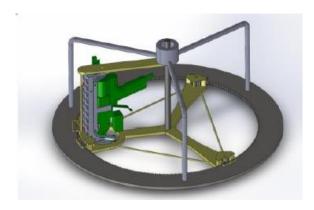
Navigation and motion control – net tracking



Net failure detection using machine vision



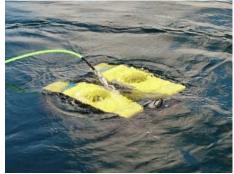
ROV-based net repair tool



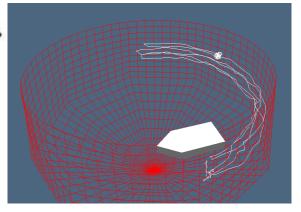


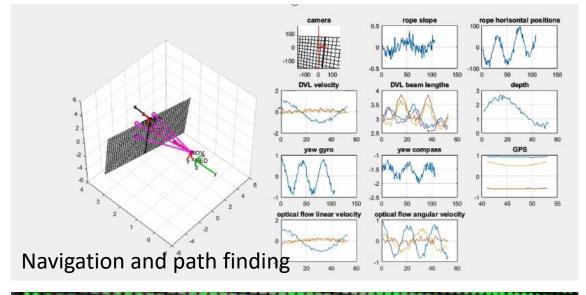
Approaches to preventing escapees

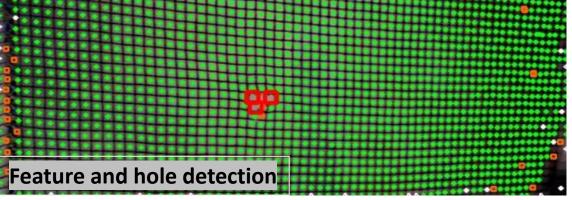










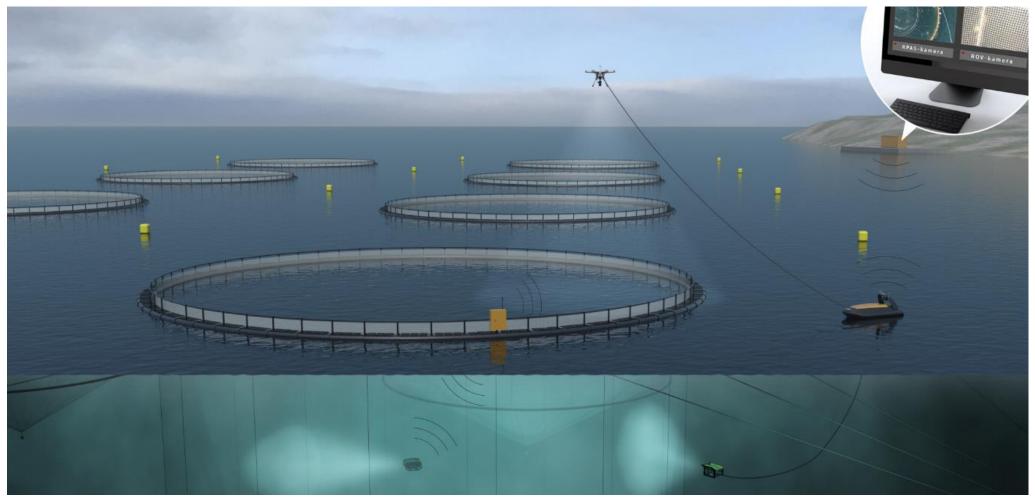






Unmanned Underwater Vehicles (UUVS):

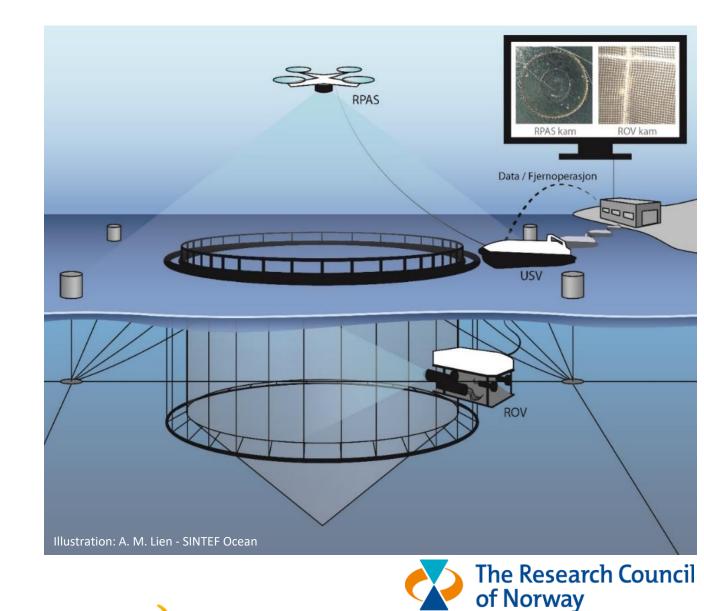
Operations in Fish Farms-ARTIFEX Project





ARTIFEX – Remotely controlled operations

Daily and periodic operations using Unmanned Surface Vehicle (USV) as carrier of ROV and RPAS (Remotely Piloted Aircraft System)

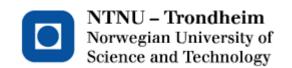










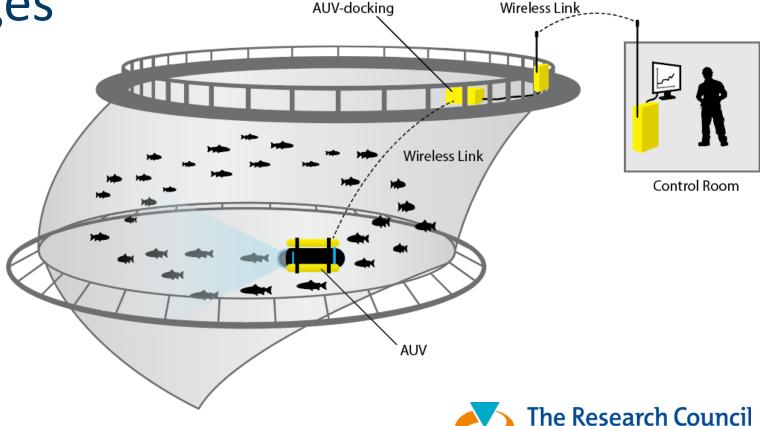




CageReporter – Autonomy and Bio-interactivity

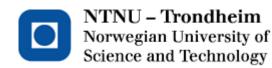
in Aquaculture Cages

Resident (24/7), autonomous, nontethered vehicle (AUV) for high quality data acquisition











of Norway

INDISAL – Individual based observation

Develop an individual biometric "finger-print" identification of each salmon













SINTEF Ocean

Autonomous Aquaculture and Robotic Lab

COMBINE BIOLOGY AND TECHNOLOGY



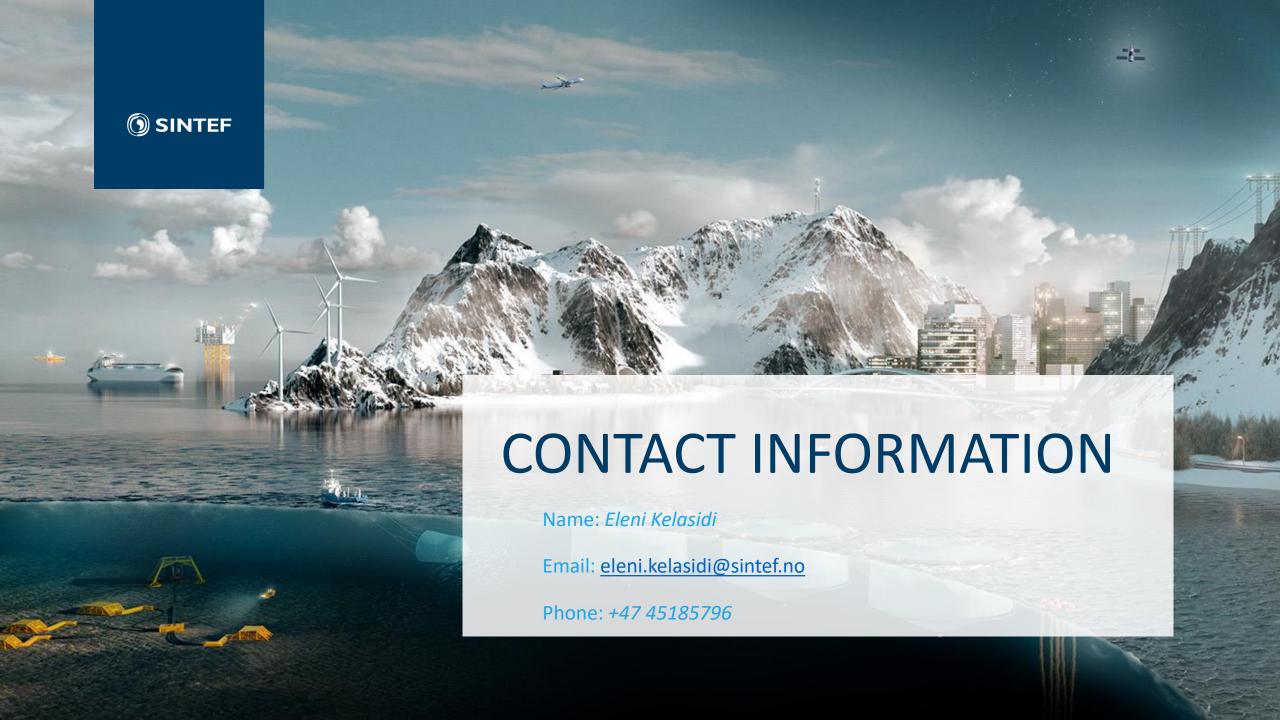
MULTIDISCIPLINARY RESEARCH



FULL SCALE VALIDATION



SOLUTIONS TO AQUACULTURE INDUSTRY





Teknologi for et bedre samfunn