

FFU Seminar 2008 – StatoilHydro IB-senter Forus

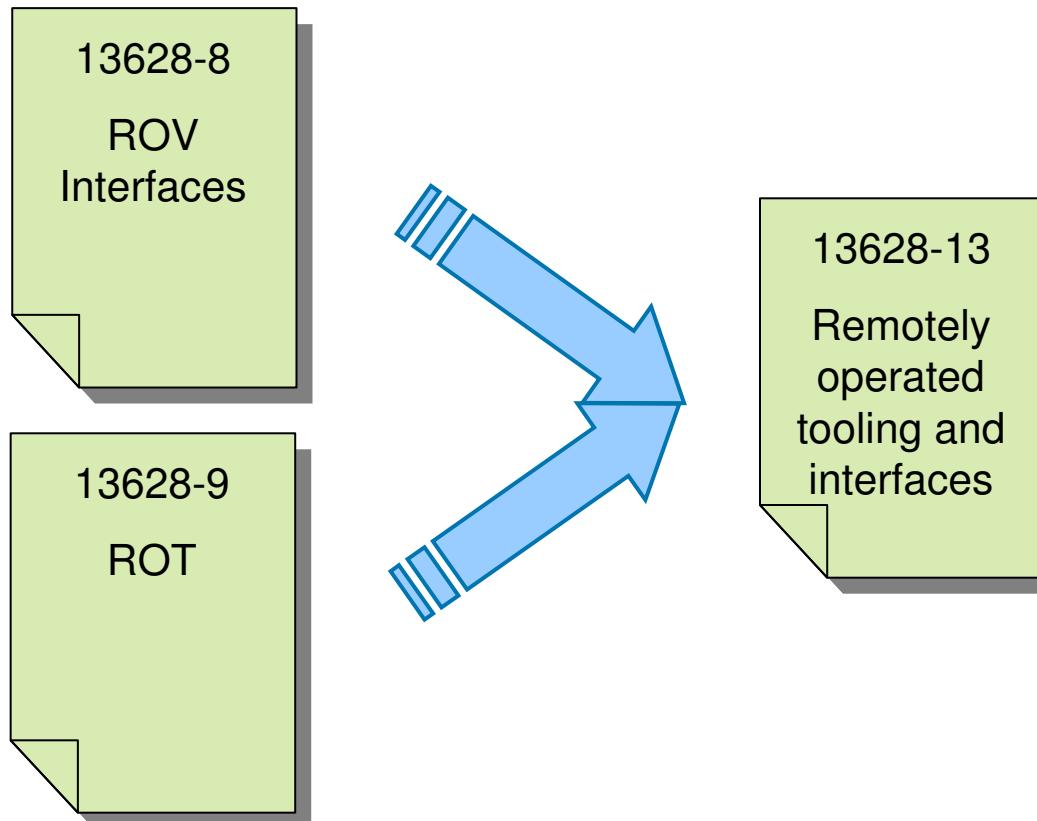
ISO 13628-13 – En ny Intervensjonsstandard

StatoilHydro

Agenda

- Bakgrunn – er det behov for en ny standard?
- Utvikling av en ny standard – samarbeid mellom ISO /API
- Hva er endringene i forhold til tidligere standarder?

Bakgrunn



Bakgrunn – utviklingstrend konvertering av eksisterende intervensionsløsninger

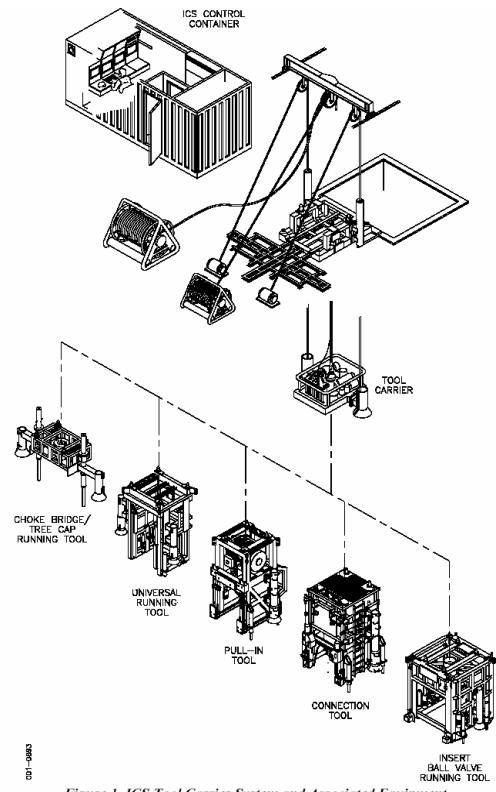
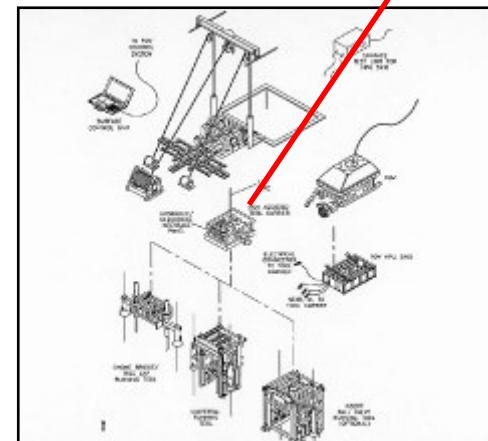
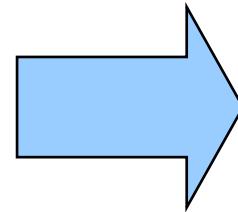


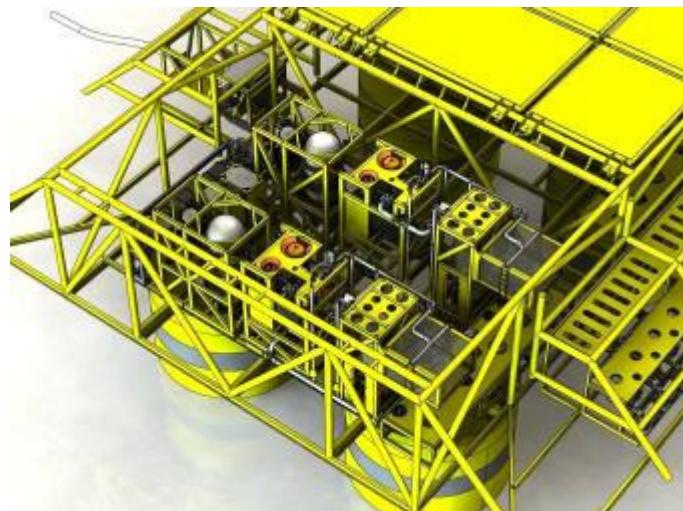
Figure 1 ICS Tool Carrier System and Associated Equipment

Opprinnelig ROT design med Dedikert Kontrollsysten

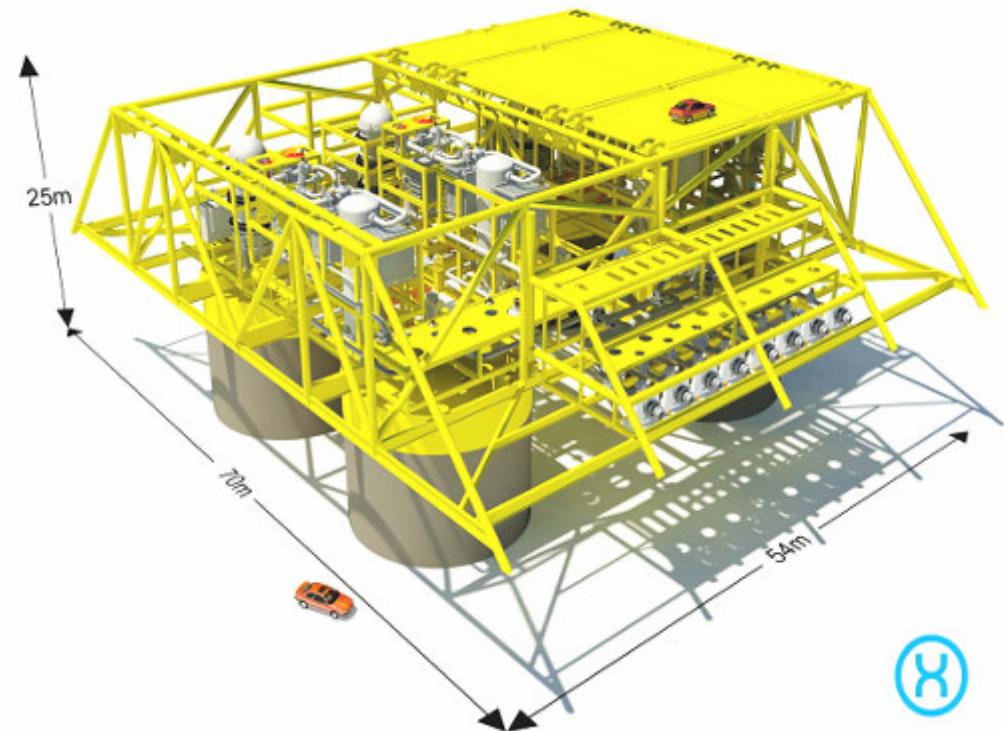


Revidert design med ROV operert kontrollsystem

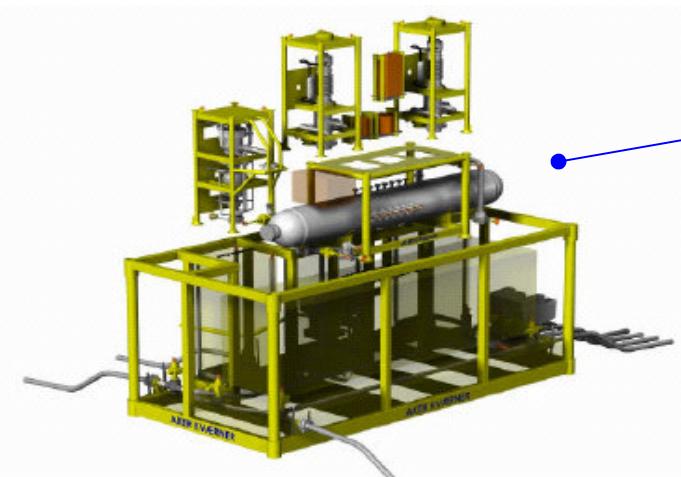
Bakgrunn – Nye subseakonsepter



Ormen Lange gasskompressjon

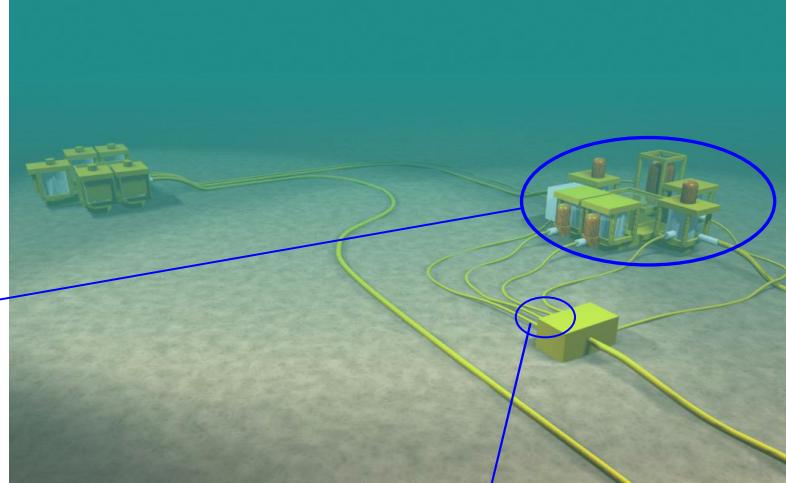


Bakgrunn – Nye subsea moduler og komponenter



Subsea Separation System

- **New equipment layout**
- **New subsea modules**



Bakgrunn – endrede intervensionsløsninger – tie-in system



GFA Sat. tie-in system



UTIS

ROT basert



ABB ICARUS

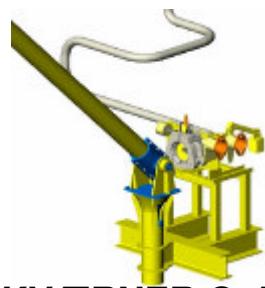


KVÆRNER RTS



FKS ROVCON

ROV basert



KVÆRNER Guide & Hingeover

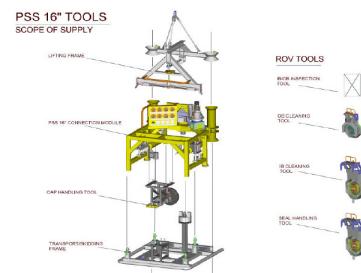


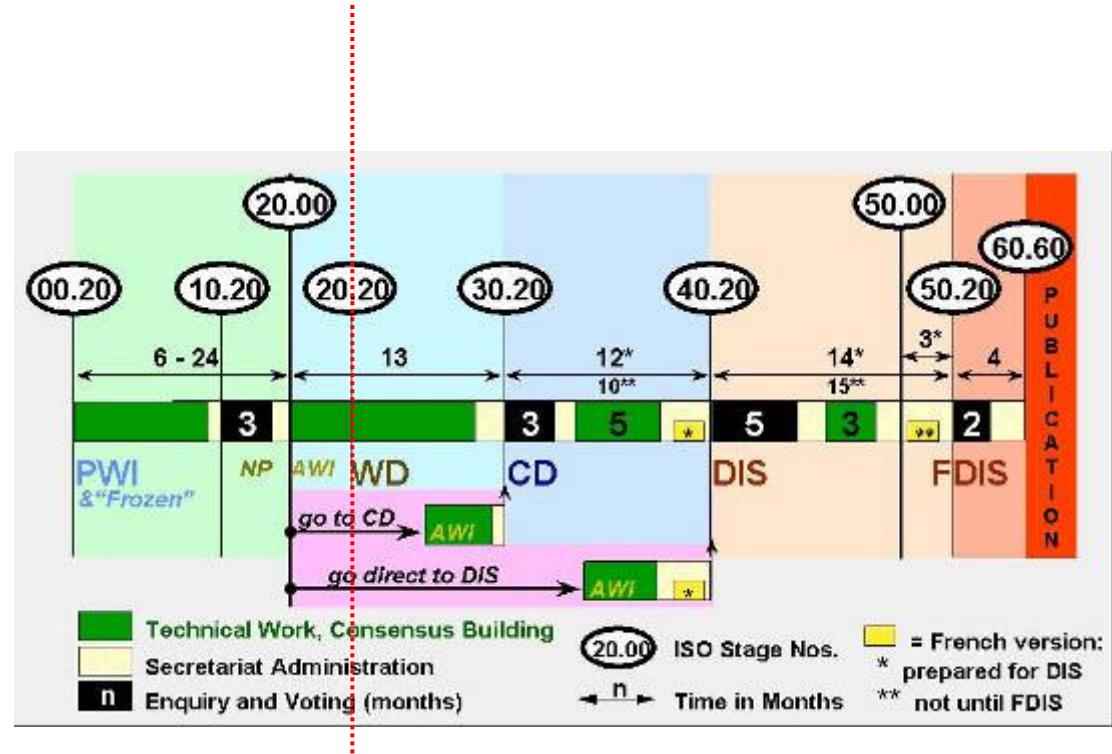
ABB PSS

ROV operert

Typisk sekvens for utvikling av en ISO standard

ISO Typical Project Programme

- 00.20 Proposal for a new project under review
- 10.20 New project ballot initiated
- 20.00 New project registered
- 20.20 Working Draft (WD) study initiated
- 30.20 CD study/ballot initiated
- 40.20 DIS ballot initiated (5 months)
- 50.00 FDIS registered for formal approval
- 50.20 FDIS ballot initiated (2 months)
- 60.60 IS standard published



Starting point

For 13628-13

ISO/API samarbeid

- Samarbeid i utvikling av ny standard
 - Egne arbeidsgrupper i ISO og API
 - Arbeidsgruppe sammensatt av representanter fra leverandørmarkedet og operatørselskap
 - Nasjonale høringsrunder med nominert ekspertpersonell



Den nye standarden 13628-13 (1)

- 1 Scope
- 2 Normative References
- 3 Terms, definitions and abbreviated terms
- 4 System Approach
 - 4.1 General
 - 4.2 System Considerations
 - 4.3 Intervention Strategies
 - 4.3.1 General
 - 4.3.2 Subsea Intervention System concept strategy development
 - 4.3.3 Intervention by ROV
 - 4.3.4 Component and Module Intervention
 - 4.3.5 Flowline and Umbilical Tie-in Systems

preliminary

Den nye standarden 13628-13 (2)

5 Subsea Intervention Systems Design Requirements

5.1 General

5.1.1 Intervention Vessel Interface Information

5.1.2 Tool handling and deployment

5.2 Surface Equipment

5.2.1 General

5.3 Module /Component Replacement Tools

5.4 ROV Intervention Systems

5.4.1 General

5.4.2 ROV Interfaces

5.4.3 ROV mounted skids

5.4.4 ROV Tools

Den nye standarden 13628-13 (3)

- 5.5 Tie-in & Connection Systems
 - 5.5.1 General
 - 5.5.2 Pull-in tool (PIT)
 - 5.5.3 Connection function
 - 5.5.4 Connector and seal assembly
 - 5.5.5 Hubs, caps and termination heads
 - 5.5.6 Pull-in porches/alignment structures
- 5.6 Subsea Intervention Tooling Control and Actuation
 - 5.6.1 General
 - 5.6.2 Common requirements control systems
 - 5.6.3 Self contained control systems
 - 5.6.4 Control systems controlled via ROV Control System
 - 5.6.5 Mechanical Actuation

Den nye standarden 13628-13 (4)

- 6 **Materials**
- 6.1 **General Requirements**
- 6.2 **Selection criteria**
- 7 **Validation and Verification**
- 7.1 **Design Validation**
- 7.1.1 **Design Documentation**
- 7.1.2 **Design Reviews**
- 7.1.3 **Factory Acceptance Testing**
- 7.2 **Design Verification**
- 7.2.1 **Qualification Testing**
- 7.2.2 **System Integration Testing**



Takk for oppmerksomheten!